

IP Geolocation with Two-Tier Neural Network

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Outline

Background

System Design

Data Collection

Evaluation

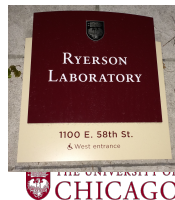
Conclusion

What is IP Geolocation?

128.135.100.110



41.79N
87.60W



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What can we do with IP Geolocation?



Credit card Fraud



CDN



Online Ads

Previous work - IPGeo Database



IP2LOCATION™



Pros

- ▶ Easy to use

Cons

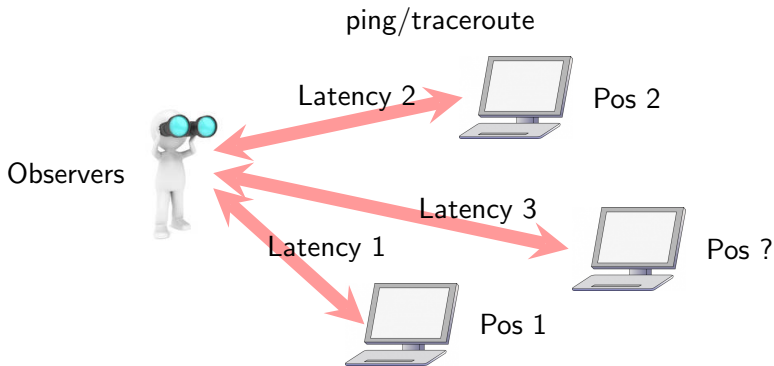
- ▶ Less accurate (City level)
- ▶ Not up to date (Periodic update)



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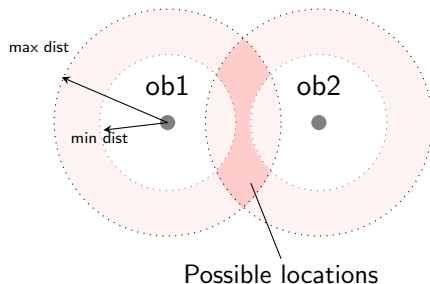
Previous work - Measuring network delay



$$\theta = \text{train}(\text{Latency}_{1,2}, \text{Pos}_{1,2})$$

$$\text{Pos}_3 = \text{predict}(\text{Latency}_3, \theta)$$

Previous work - Build a model



Design a simple model (mostly based on triangulation) and calculate the parameters. [GZCF06, KBJK⁺06, WSS07, DPCS12]

Accuracy: ~ 10 km median error

Such a model requires a lot of assumptions, which are not necessarily true. (E.g., is there a linear relationship between latency and geographic distance?)

Previous work - What do we learn

- ▶ Physically adjacent nodes have similar measurements
- ▶ Network topology is simpler in a local area than in a larger area



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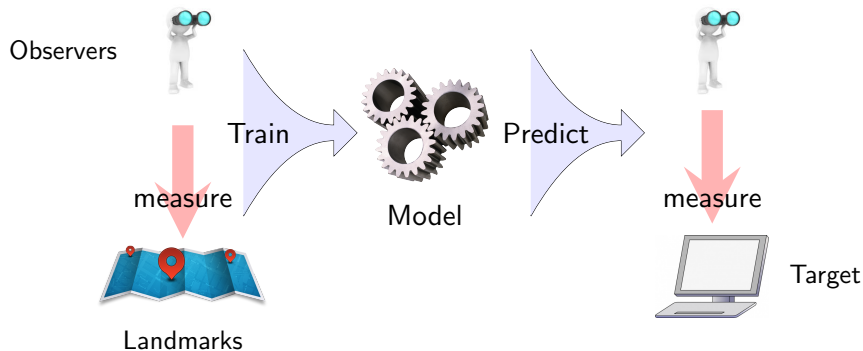
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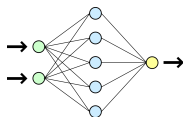
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Design Idea

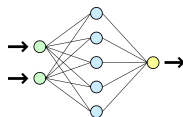
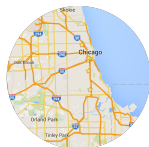


Our method employs machine learning technique to solve the problem. Instead of “choose” a model, we collect latency data from landmarks with known locations and train a model, then use this model to predict the location of unknown targets.

Two-Tier Neural Network



Region estimation



Location estimation

Intuition:

Measurement from adjacent landmarks can yield a better estimation result.

Make a rough estimation with all landmarks, locate the region the target resides in. Then use only the landmarks in that region to do a more accurate prediction.



Data Collection - Datasets



A large enough landmark dataset is crucial to the accuracy of our method. Our dataset consists of landmarks from three data sources

- ▶ Ripe Atlas Probes
- ▶ University Webservers
- ▶ City Government Webservers

Data Collection

University Dataset

- ▶ Get a U.S. university list from Wikipedia
- ▶ Use Google search API to obtain the geographic location and its website
- ▶ Use `host` command to obtain corresponding IP address

City Dataset

- ▶ Get a U.S. city and population list from government website
- ▶ Choose the top 50 cities of each state ordered by population in descending order
- ▶ Use Google search API to obtain the geographic location and its website
- ▶ Use `host` command to obtain corresponding IP address



Data Collection - Result

Category	Raw	Valid	Reachable
Ripe Atlas Probes	637	637	429
University Websites	2170	1858	826
City Government Websites	2880	740	292
Total	5687	3235	1547

Table: Landmark Detail (Raw: All landmark candidates. Valid: Landmarks after filtering and cross-validation. Reachable: Landmarks that respond to ping)

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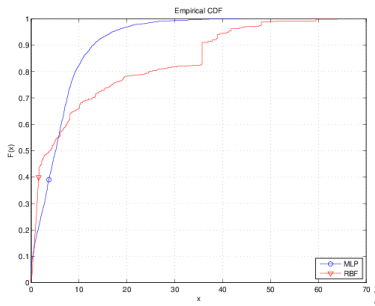
System Design

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Evaluation - Error Distribution



Error Distribution of the estimation result

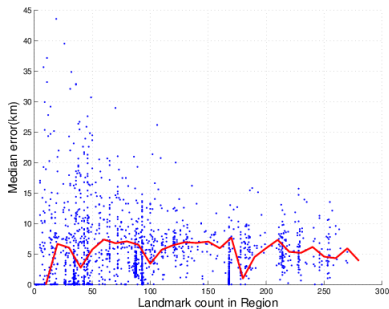
We compare the performance of two popular neural network types: Multi-Layer Perceptron (MLP) and Radial-Basis Function (RBF)

Accuracy:

- ▶ Over 80% estimations have a error within 10km
- ▶ MLP has a overall better performance than RBF



Evaluation - Accuracy related to number of landmarks



MLP Error related to Landmark Density

- ▶ 3.7km in regions with > 100 landmarks
- ▶ 6km in regions with < 50 landmarks
- ▶ Error decreases when landmark density increases



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Our Contribution:

- ▶ A novel method for IP Geolocation
- ▶ Achieved similar accuracy with state-of-the art with a fixed amount of landmarks

Question?

